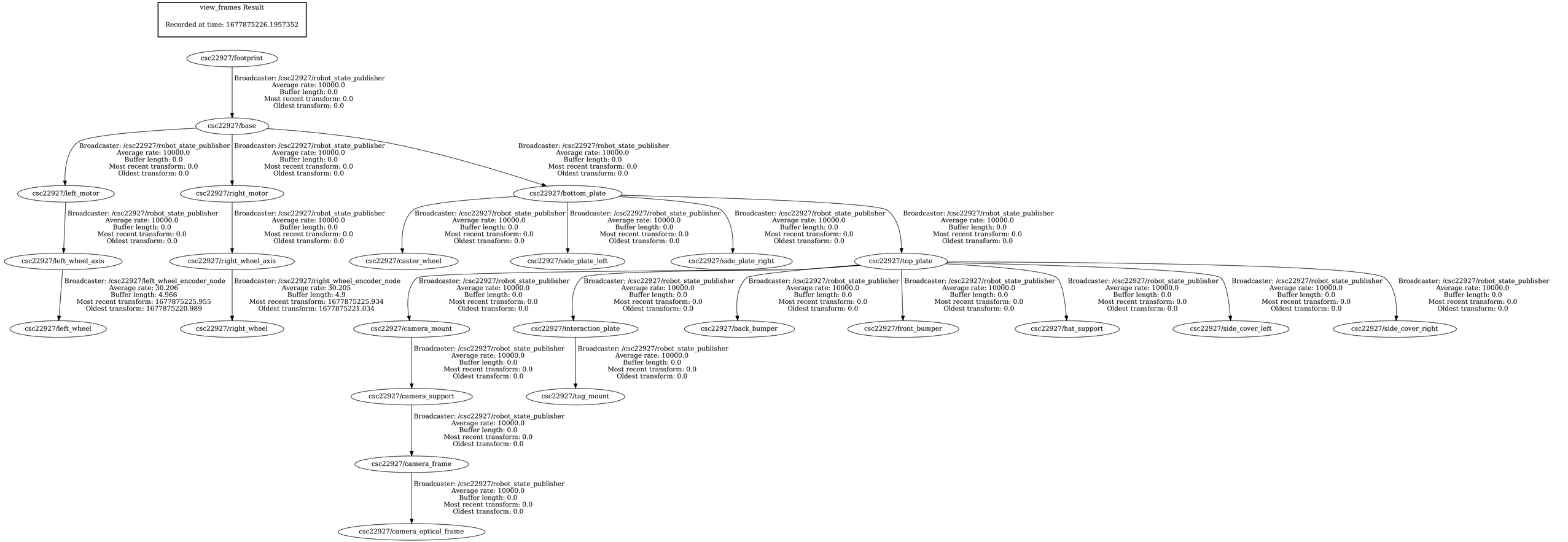
view_frames Result
Recorded at time: 1677875226.1957352
csc22927/footprint
Broadcaster: /csc22927/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
csc22927/base
Broadcaster: /csc22927/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
Broadcaster: /csc22927/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
Broadcaster: /csc22927/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
csc22927/left_motor
csc22927/right_motor
csc22927/bottom_plate
Broadcaster: /csc22927/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
Broadcaster: /csc22927/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
Broadcaster: /csc22927/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
Broadcaster: /csc22927/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
Broadcaster: /csc22927/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
Broadcaster: /csc22927/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
Broadcaster: /csc22927/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
csc22927/left_wheel_axis
csc22927/right_wheel_axis
csc22927/caster_wheel
csc22927/side_plate_left
csc22927/side_plate_right
csc22927/top_plate
Broadcaster: /csc22927/left_wheel_encoder_node
Average rate: 30.206
Buffer length: 4.966
Most recent transform: 1677875225.955
Oldest transform: 1677875220.989
Broadcaster: /csc22927/right_wheel_encoder_node
Average rate: 30.205
Buffer length: 4.9
Most recent transform: 1677875225.934
Oldest transform: 1677875221.034
Broadcaster: /csc22927/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
Broadcaster: /csc22927/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
Broadcaster: /csc22927/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
Broadcaster: /csc22927/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
Broadcaster: /csc22927/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
Broadcaster: /csc22927/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
Broadcaster: /csc22927/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
csc22927/left_wheel
csc22927/right_wheel
csc22927/camera_mount
csc22927/interaction_plate
csc22927/back_bumper
csc22927/front_bumper
csc22927/hat_support
csc22927/side_cover_left
csc22927/side_cover_right
Broadcaster: /csc22927/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
Broadcaster: /csc22927/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
csc22927/camera_support
csc22927/tag_mount
Broadcaster: /csc22927/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
csc22927/camera_frame
Broadcaster: /csc22927/robot_state_publisher
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0
csc22927/camera_optical_frame